

## Defination

linear Equation:  $a_1x_1 + \dots + a_nx_n = b$

where  $a_1, a_2 \dots$  are numbers and  $x_1, \dots, x_n$  are variables

eg.

$4x_1 - 5x_2 + 2 = x_1$	$\Leftrightarrow 3x_1 - 5x_2 = -2$	✓
$x_2 = 2(\sqrt{6} - x_1) + x_3$	$\Leftrightarrow 2x_1 + x_2 - x_3 = 2\sqrt{3}$	✓
$4x_1 - 6x_2 = x_1x_2$		✗
$x_2 = 2\sqrt{x_1} - 7$		✗

linear System: Collection of one or more linear equations

Solution: linear system's solution is a list  $(s_1, s_2, s_3, \dots, s_n)$

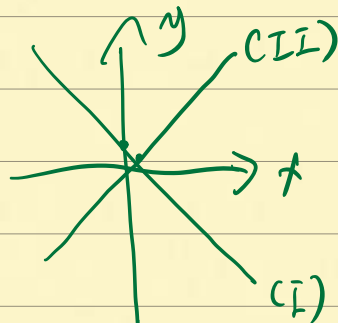
eg.

(I)	$x_1 + x_2 = 1$	
(II)	$-x_1 + x_2 = 0$	solution?

① Add I and II:  $2x_2 = 1 \Rightarrow x_2 = 1/2$

② plug into I  $x_1 + 1/2 = 1 \Rightarrow x_1 = 1/2$

③ Thus  $(x_1, x_2) = (1/2, 1/2)$  is the only solution.



Not every system have only one solution.

eg.

$$\begin{aligned}x_1 - 2x_2 &= -3 \quad (III) \\ 2x_1 - 4x_2 &= 8 \quad (IV)\end{aligned}$$

① Multiply I by 2  $\Rightarrow 2x_1 - 4x_2 = -6$

② Subtract (I) from (IV)

$\Rightarrow 0 = 14$  which is always false.

$\Rightarrow$  No solution exist

eg.

$$\begin{aligned}x_1 + x_2 &= 3 \quad (V) \\ -2x_1 - 2x_2 &= 6 \quad (VI)\end{aligned}$$

Multiply V by 2  $\Rightarrow 2x_1 + 2x_2 = 6$

V and VI have same value just set

$x_2 = -3 - x_1$ , equation has inf solution

**Summary:** A linear system has either:  $\left\{ \begin{array}{l} \text{One unique solution} \\ \text{No solution} \\ \text{inf many solutions} \end{array} \right.$

**Equivalent:** Two linear systems are equivalent if they have the same solution set

## Matrix and Linear System

**Definition:** A  $m \times n$  matrix is a rectangular array of number with  $m$  rows and  $n$  columns.

eg.  $\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}, \begin{bmatrix} 1 & 2 & 3 \\ 2 & 1 & 4 \end{bmatrix}, \begin{bmatrix} 1 & 2 \\ 2 & 4 \\ 3 & 6 \end{bmatrix}, [1 + j5]$

Entries:  $A = \begin{bmatrix} a_{11} & a_{12} & \dots \\ a_{21} & a_{22} & \dots \\ \vdots & \vdots & \ddots \\ a_{m1} & a_{m2} & \dots \end{bmatrix}$   $a_{ij}$ :  $i$  row  $j$  column

linear system	coefficient matrix	augmented matrix
$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$	$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$	$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} &   & b_1 \\ a_{21} & a_{22} & \dots & a_{2n} &   & b_2 \\ \vdots & \vdots & \ddots & \vdots &   & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} &   & b_m \end{bmatrix}$
$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$		
$\vdots$		
$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$		

### Elementary row operation

① Replacement: Add a multiple of one row to another row.

$$R_i \rightarrow R_i + cR_j, \text{ where } i \neq j$$

② Interchange: Interchange two rows:  $R_i \leftrightarrow R_j$

③ Scaling: Multiply all entries in a row by a nonzero constant:  $R_i \rightarrow cR_i, \text{ where } c \neq 0$

eg.  $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \xrightarrow[\text{Replacement}]{R_2 \rightarrow R_2 + 3R_1} \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix}$

$\begin{bmatrix} 1 & 0 \\ 0 & 2 \\ 2 & 3 \end{bmatrix} \xrightarrow[\text{Interchange}]{R_1 \leftrightarrow R_3} \begin{bmatrix} 2 & 3 \\ 0 & 1 \\ 1 & 0 \end{bmatrix}$

$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \xrightarrow{R_2 \rightarrow 3R_2} \begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix}$

eg. Consider a row operation  $R_3 \rightarrow R_3 + 3R_1$ , Is there any operation reverse it?

$$R_3 \rightarrow R_3 - 3R_1$$

Replacing

**Summary:** Every Row operation is reversible, like:

Scaling:  $R_2 \rightarrow cR_2 : R_2 \rightarrow \frac{1}{c}R_2$ .

Interchange:  $R_1 \leftrightarrow R_2 : R_1 \leftrightarrow R_2$

**Row equivalent:** Two matrix are row equivalent if one matrix can be transform into the other matrix by a sequence of elementary row operation

**Theorem 1:** If the augmented matrix of two linear systems are row equivalent, then the two systems have the same solution set

eg. 
$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_3 \rightarrow R_3 + 3R_1} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix} \xrightarrow{R_3 \rightarrow R_3 - 3R_1} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

↓  
Row Equivalent

Echelon form (or row echelon form)

Define: A matrix is in Echelon form if:

- ① All non zero rows (rows with at least one nonzero element) are above any rows of all zeros.
- ② The leading entry (the first nonzero number from left) of a nonzero row is always strictly to the right of the leading entry of the row above it.

eg. 
$$\begin{bmatrix} 3 & 1 & 2 & 0 & 5 \\ 0 & 2 & 0 & 1 & 4 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$
 ← nonzero row 1. ✓  
 Leading Entry 3  $\searrow$  Right 2 ✓  
 $\Rightarrow$  True

$$\begin{bmatrix} 0 & 2 & 0 & 1 & 4 \\ 3 & 1 & 2 & 0 & 5 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$
 1. ✓  
 2. ✗  $\Rightarrow$  False

$$\begin{bmatrix} 2 & -2 & 3 \\ 0 & 5 & 0 \\ 0 & 0 & 5/2 \end{bmatrix}$$
 1. ✓  
 2. ✓  $\Rightarrow$  True

$$\begin{bmatrix} 0 & 1 & 3 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$
 1. ✓  
 2. ✓  $\Rightarrow$  True

Row Reduced echelon Form (or reduced echelon form or RREF)

Requir: ① is echelon form

② The leading entry in each non-zero row is 1

③ Each leading Entry is the only non-zero entry

in the column

eg.

$$\text{a) } \begin{bmatrix} 0 & 1 & 3 & 0 & 0 & 2 & 5 & 0 & 0 & 6 \\ 0 & 0 & 0 & 1 & 0 & 1 & \frac{1}{2} & 0 & 0 & -2 \\ 0 & 0 & 0 & 0 & 1 & -3 & 4 & 0 & 0 & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 \end{bmatrix}$$

- ① ✓
- ② ✓  $\Rightarrow$  True
- ③ ✓

$$\begin{bmatrix} 1 & 0 & -2 & 3 & 2 & -24 \\ 0 & 1 & -2 & 2 & 0 & -7 \\ 0 & 0 & 0 & 0 & 1 & 4 \end{bmatrix}$$

X

- ① ✓
- ② ✓ = False
- ③ X

**Theorem 1** Each matrix is row equivalent to one and only one matrix in reduced echelon form

**def:** We say that matrix  $B$  is RREF of matrix  $A$  if  $A$  and  $B$  are row-equivalent and  $B$  is in RREF.

eg. Find RREF of the matrix:

$$\begin{bmatrix} 3 & -9 & 12 & -9 & 6 & 15 \\ 3 & -7 & 8 & -5 & 8 & 9 \end{bmatrix}$$

$$\text{① } R_2 = R_2 - R_1 \Rightarrow \begin{bmatrix} 3 & -9 & 12 & -9 & 6 & 15 \\ 0 & 2 & -4 & 4 & 2 & -6 \end{bmatrix}$$

$$\text{② } R_1 = R_1 \cdot \frac{1}{3} \Rightarrow \begin{bmatrix} 1 & -3 & 4 & -3 & 2 & 5 \\ 0 & 2 & -4 & 4 & 2 & -6 \end{bmatrix}$$

$R_2 = R_2 \cdot \frac{1}{2}$

$$\textcircled{3} R_1 = R_1 + 3R_2 \Rightarrow \begin{bmatrix} 1 & 0 & -2 & 3 & 5 & -4 \\ 0 & 1 & 2 & 2 & 1 & -3 \end{bmatrix}$$

**Pivot position**: the position of the leading entry in an echelon form of a matrix. the pivot column is the column that contains a pivot position

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**Example.** Locate the pivot columns of the following matrix.

$$A = \begin{bmatrix} 1 & -3 & -6 & 4 & 9 \\ -1 & 2 & -1 & 3 & 1 \\ 1 & 4 & 5 & -9 & -7 \end{bmatrix}$$

**Solution.**

$$\begin{array}{l} \xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ -1 & -2 & -1 & 3 & 1 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix} \quad \xrightarrow{R_2 \rightarrow R_2 + R_1} \begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ 0 & 2 & 4 & -6 & -6 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix} \\ \xrightarrow{R_3 \rightarrow R_3 + 1.5R_2} \begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ 0 & 2 & 4 & -6 & -6 \\ 0 & 0 & 0 & -5 & 0 \end{bmatrix} \end{array}$$

Thus columns 1, 2, 4 of A are the pivot columns of A.

**Basic variable (or pivot variable)**: is a variable that corresponds to a pivot column in the coefficient matrix of a linear system. A **free variable** that is not a pivot variable.

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$$\left[ \begin{array}{ccc|ccc} 1 & 6 & 3 & 0 & 0 & 0 \\ 0 & 0 & -8 & 0 & 0 & 5 \\ 0 & 0 & 0 & 0 & 1 & 7 \end{array} \right] \Rightarrow \begin{array}{l} x_1, x_3, x_5 \text{ are basic} \\ \text{variable} \\ x_2, x_4 \text{ are free} \\ \text{variable} \end{array}$$

$x_1 \quad x_2 \quad x_3 \quad x_4 \quad x_5$